

Math 4997-3

Lecture 17: Distributed implementation of the 1D heat equation

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<https://www.cct.lsu.edu/~pdiehl/teaching/2021/4997/>

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Reminder

Serialization

Adding components and actions

Preparing the simulation control to be distributed

Scaling results

Summary

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Reminder

Lecture 16

What you should know from last lecture

- ▶ Serialization
- ▶ Distributed computing
 - ▶ Plain actions
 - ▶ Components
 - ▶ Components actions

Serialization

Adding serialization

Note even if all the code in this iteration runs for now only one one locality (node), we have to add serialization since all arguments passed to an action have to support serialization.

```
// We have to add this class as a friend
friend class hpx::serialization::access;

// Add a function to serialize all arguments
template <typename Archive>
void serialize(Archive& ar,
               const unsigned int version) const {}
```

Note that we will implement this function in the next lecture when we prepare the code to run on multiple localities.

Notes

Extending the partition data with serialization

```
class partition_data
{
private:
    // Note we have to make the unique_ptr to
    // a shared_ptr since we share the data
    std::shared_ptr<double[]> data_;
    std::size_t size_;

    friend class hpx::serialization::access;

    template <typename Archive>
    void serialize(Archive& ar,
                  const unsigned int version) const {}
};
```

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Adding components and actions

Adding a server to handle the partitions I

```
struct partition_server
: hpx::components::component_base<partition_server>
{
// construct new instances
partition_server() {}

partition_server(partition_data const& data)
: data_(data)
{}

private:
partition_data data_;
};
```

Notes

Adding component action to the server II

```
struct partition_server
: hpx::components::component_base<partition_server>
{
// access data
partition_data get_data() const
{
return data_;
}

// Every member function which has to be invoked
// remotely needs to be wrapped into a
// component action.
HPX_DEFINE_COMPONENT_DIRECT_ACTION(
partition_server,
get_data, get_data_action);
};
```

Notes

Register the component and component action

```
// Register the component

typedef hpx::components::component<partition_server>
partition_server_type;
HPX_REGISTER_COMPONENT(partition_server_type,
partition_server);

// Register the component action

typedef partition_server::get_data_action
get_data_action;
HPX_REGISTER_ACTION(get_data_action);
```

Notes

Writing the client helper class I

```
struct partition
: hpx::components::client_base<partition,
partition_server>
{

typedef hpx::components::client_base<partition,
partition_server> base_type;

partition() {}

// Create new component on locality 'where'
// and initialize the held data
partition(hpx::id_type where, std::size_t size,
double initial_value)
: base_type(hpx::new_
<partition_server>(where, size,
initial_value))
{}
};
```

Notes

Writing the client helper class II

```
struct partition
: hpx::components::client_base<partition,
  partition_server>
{
    // Create a new component on the locality co-located
    // to the id 'where'. The new instance will be
    // initialized from the given partition_data.
    partition(hpx::id_type where,
              partition_data && data)
        : base_type(hpx::new_<partition_server>
                    (hpx::colocated(where), std::move(data)))
    {}
};
```

Notes

Writing the client helper class III

```
struct partition
: hpx::components::client_base<partition,
  partition_server>
{
    // Attach a future representing a
    // (possibly remote) partition.
    partition(hpx::future<hpx::id_type> && id)
        : base_type(std::move(id))
    {}
};
```

Notes

Writing the client helper class IV

```
struct partition
: hpx::components::client_base<partition,
  partition_server>
{
    // Unwrap a future<partition> (a partition already
    // holds a future to the id of the referenced object,
    // thus unwrapping accesses this inner future).
    partition(hpx::future<partition> && c)
        : base_type(std::move(c))
    {}
};
```

Notes

Writing the client helper class V

```
struct partition
: hpx::components::client_base<partition,
  partition_server>
{
    // Invoke the (remote) member function which
    // gives us access to the data.
    hpx::future<partition_data> get_data() const
    {
        return hpx::async(get_data_action(), get_id());
    }
};
```

Notes

Preparing the simulation control to be distributed

Updating the computation of the heat

```
static partition heat_part(partition const& left,
    partition const& middle, partition const& right)
{
return dataflow(
    unwrapping(
        [middle](partition_data const& l,
            partition_data const& m,
            partition_data const& r)
        {
            // The new partition_data will be allocated
            // on the same locality as 'middle'.
            return partition(middle.get_id(),
                heat_part_data(l, m, r));
        }
    ),
    left.get_data(), middle.get_data(),
    right.get_data());
}
```

Notes

Updating the computation of the heat II

```
stepper::space stepper::do_work(std::size_t np,
    std::size_t nx, std::size_t nt)
{
    // Initial conditions:  $f(0, i) = i$ 
    for (std::size_t i = 0; i != np; ++i)
        U[0][i] = partition(hpx::find_here(),
            nx, double(i));
}
```

Note that we only use `hpx::find_here()` the code will run one one locality only.

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Updating the computation of the heat III

```
// Generate place holder for the changing arguments
using hpx::util::placeholders::_1;
using hpx::util::placeholders::_2;
using hpx::util::placeholders::_3;

// Pass the fixed argument to the function
auto Op = hpx::util::bind(heat_part_action(),
    hpx::find_here(), _1, _2, _3);

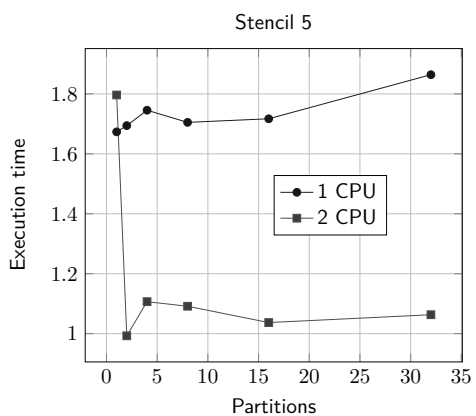
next[i] = dataflow(
    hpx::launch::async, Op,
    current[idx(i, -1, np)],
    current[i],
    current[idx(i, +1, np)]
);
```

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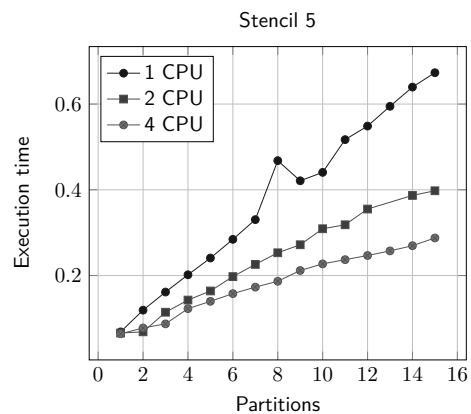
Scaling results

Scaling for 1000000 discrete mesh points



Notes

Scaling for increasing amount of work



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Summary

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After this lecture, you should know

- ▶ How to use components and actions to make remote function calls

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